



GPL951XXUA CTS Driver Code User's Manual

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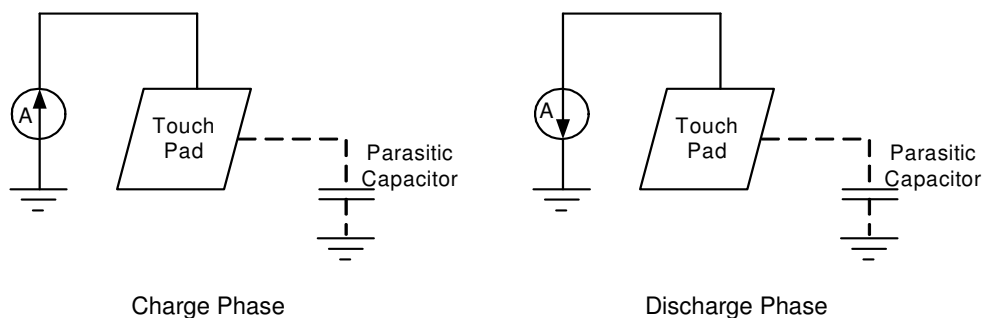
Revision History

Revision	Date	By	Remark
0.1	2016.09.02	Frank Kung	First Edition

1 Introduction

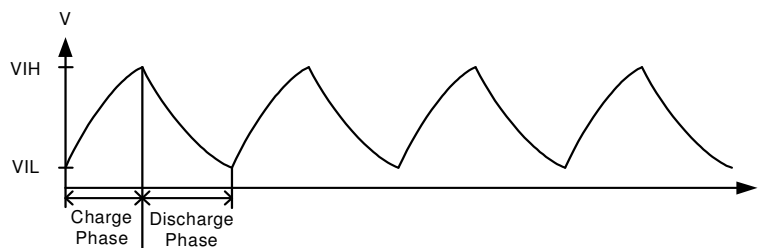
GPL951XXUA provides one Capacitor Touch Sensor Interface (CTS), this driver code can help users to develop CTS application easily. CTS Driver Code provides C-language and assembly functions for customer applications. This driver code also reserved some CTS driver control parameters to make user fine-tune CTS sensitive and error touch preventing.

A capacitor touch sensor circuit is showed as below:



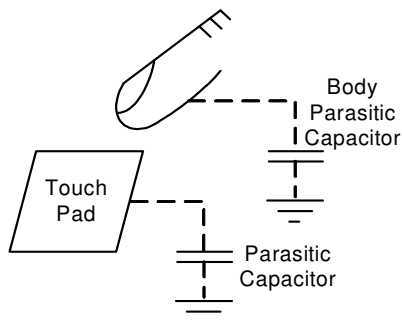
Where Charge and Discharge current is register control, Programmers can modify it in CTS_User.asm
One CTS Scan Time is the period time length of one charge and discharge cycle.

The waveform is showed as below:

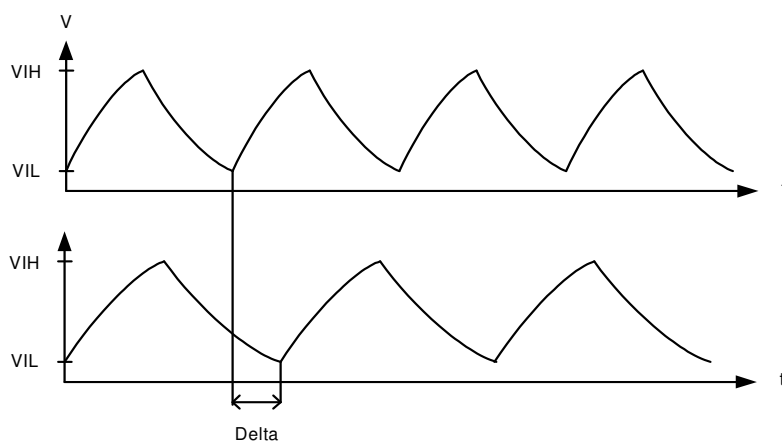


Where VIH and VIL are register control, Programmers can modify it in CTS_User.asm

When user is touching Touch Pad, the total capacitor value is circuit parasitic capacitor + user body parasitic capacitor, show as below



The waveform changing with and without touching is showed as below:



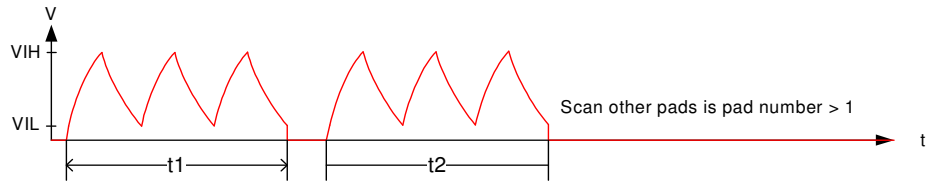
The CTS driver code will refer to Delta value to judge this touch pad is touched or not.

In driver code, user can modify variable R_ScanNumber, R_ThresholdOn, R_ThresholdOff and R_ScanCycleNum.

R_ScanNumber is the charge/discharge count for one cycle. R_ScanNumber variable number is equal to touch pad number to define each touch pad charge/discharge count.

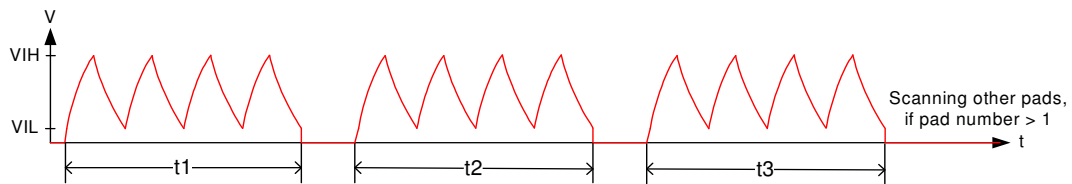
R_ScanCycleNum is the cycle number of charge/discharge cycle count. The total charge/discharge time (R_CtsSum) is $(t \text{ of } R_ScanNumber) * R_ScanCycleNum$.

Example1: R_ScanNumber = 3, R_ScanCycleNum = 2



This pad total charge/discharge time R_CtsSum is $t1 + t2$

Example2: $R_ScanNumber = 4$, $R_ScanCycleNum = 3$



This pad total charge/discharge time R_CtsSum is $t1 + t2 + t3$

$$R_TriggerLevel = R_CtsSum - R_CtsRefer$$

$R_ThresholdOn$ is the threshold of on level, when $R_TriggerLevel \geq R_ThresholdOn$ means touch pad is touched.

$R_ThresholdOff$ is the threshold of off level, when $R_TriggerLevel < R_ThresholdOff$ means touch pad is not touched.

2 Function List for Assembly

CTS Driver Function List			
Function	Parameter	Return	Description
F_CTS_Version	None	R1	CTS Driver code version V1.0, R1=0x0100
F_CTS_Initial	None	None	CTS Driver variable and HW Initialize
F_CTS_ScanStart	None	None	CTS Scanning start
F_CTS_ISR	None	None	CTS Driver interrupt service
F_CtsForceCali	R1: Calibration Count	None	Force CTS Driver Calibration
F_CTS_ServiceLoop	None	None	CTS Service loop

CTS User's Function List			
Function	Parameter	Return	Description
F_CTS_User_Init	None	None	CTS HW initial
F_CTS_Para_User_Initial	None	None	CTS Default Parameters initial
F_CTSSetScanNum	R4: Pad Index	None	Set CTS Scan number
F_CTSChSel	R4: Pad Index	None	Set CTS Scan IO selection register
F_CTSSStart	None	None	CTS Scanning Start
F_CTSAllChOff	None	None	Stop All CTS Scan and Clear Scan IO setting

3 Global Variable for Assembly

3.1 CTS Driver Global Variable

Name	Size(word)	Description
R_CtsSum	1 X Pad Number	Pad total scan time (Current value)
R_CtsReferL R_CtsRefer	2 X Pad Number	No Touch total scan time (Reference value).
R_SensorStatus	Bit Flag word number	Pad touch status (bit mask) 0: Touch release 1: Touched
R_CTS_Key	Bit Flag word number	Pad touch result (bit mask) 0: Touch release 1: Touched
R_TriggerLevel	Pad Number	CTS Sum - CTS Reference
R_ScanDoneFlag	1	CTS Scan completed Flag This flag is set by driver code, and cleared by user 0: CTS is scanning 1: CTS scan is completed
R_ScanNumber	Pad Number	Scan Number for each CTS IO
R_ThresholdOn	Pad Number	Touch On Threshold Level for each CTS IO
R_ThresholdOff	Pad Number	Touch Off Threshold Level for each CTS IO
R_ScanCycleNum	1	Scan Cycle Number

4 Global Table for Assembly

4.1 CTS Driver Global Table

Name	Size(word)	Description
T_TotalPadNum	2	CTS Pad number - 1
T_TraceUpStep	1	CTS Reference adaptive trace up step
T_TraceDownStep	1	CTS Reference adaptive trace down step
T_CalibrationCount	1	CTS driver calibration default count
T_ReferenceErrCnt	1	CTS reference level error de-bounce count
T_CtsKeyDebounceTime	1	CTS Touch de-bounce count
T_ScanLine	Pad Number	CTS Pad bit map
T_CTS_IOSel	Pad Number	CTS HW IO selection register setting
T_ScanNum	Pad Number	CTS Pad scan number setting value

5 Resource

5.1 CTS Driver Code

5.1.1 RAM Size

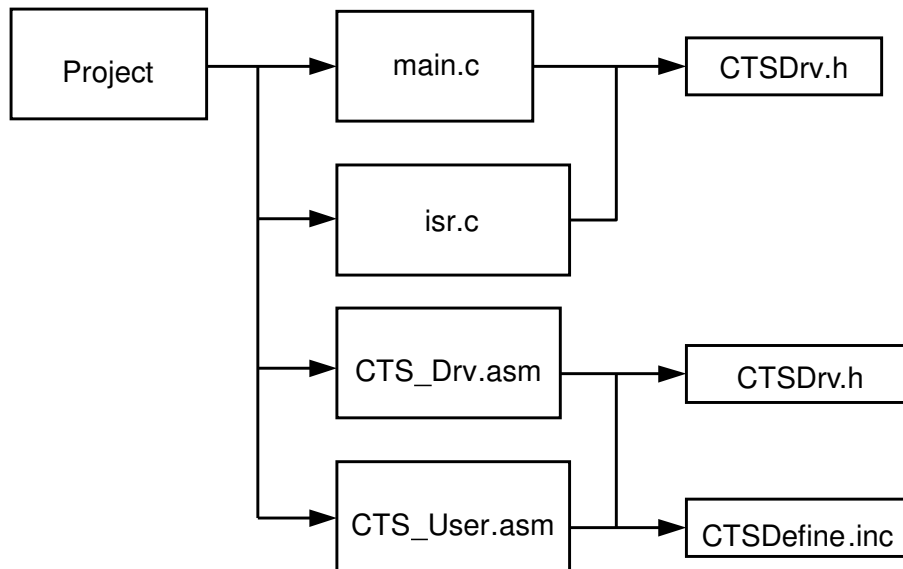
Overlap RAM (word)	Non-overlap RAM (word)
0	6 + 8xPad Number

5.1.2 ROM Size

Code (word)	DATA (word)
650 + 5 x Pad Number	0

6 Project Architecture for Assembly

6.1 Architecture



7 Application Interface for Assembly

7.1 CTS User Code

7.1.1 F_CTS_User_Init

Description	CTS HW initial
Parameters	None
Return Values	None
Destroy	R1, R2, R3
Remarks	This function will be call in function F_CTS_Initial
Example	<pre> F_CTS_User_Init: call F_CTS_Para_User_Initial r1 = 0xFFFF [P_IOF_Dir] = r1 [P_IOF_Attrib] = r1 r1 = C_IOF_CTS_En [P_IOF_Mux] = r1 r1 = C_CTS_SYS_DIV2 [P_CTS_DIV] = r1 r1 = C_CTS_LDO33_En [P_CTS_Ctrl3] = r1 r1 = C_CTS_ScanAllDoneIntEn [P_CTS_Ctrl2] = r1 r1 = C_CTS_Current_600u + C_CTS_Duration_450n + C_CTS_NF_200M + C_CTS_TriEn + D_CtsVrefSel_275_025 [P_CTS_Ctrl1] = r1 retf </pre>

7.1.2 F_CTS_Para_User_Initial

Description	CTS HW initial
Parameters	None
Return Values	None
Destroy	R1, R2, R3
Remarks	<p>Users need to initialize Scan Number, On Threshold level, Off Threshold level and Scan Cycle Number.</p> <p>In example code, CTS parameter is get from default tables, user can modify the parameter data source by self.</p>
Example	F_CTS_Para_User_Initial:

	<pre> r1 = seg16 T_ScanNum ds = r1 r1 = D_SinglePadNum-1 L_Initial_Para: r2 = T_ScanNum r2 = r2 + r1 r3 = DS:[r2] r2 = R_ScanNumber r2 = r2 + r1 [r2] = r3 r2 = T_OnThresholdLevel r2 = r2 + r1 r3 = DS:[r2] r2 = R_ThresholdOn r2 = r2 + r1 [r2] = r3 r2 = T_OffThresholdLevel r2 = r2 + r1 r3 = DS:[r2] r2 = R_ThresholdOff r2 = r2 + r1 [r2] = r3 r1 = r1 - 1 jpl L_Initial_Para r1 = seg16 T_ScanCycleCnt ds = r1 r1 = T_ScanCycleCnt r2 = DS:[r1] [R_ScanCycleNum] = r2 retf </pre>
--	--

7.1.3 F_CTSSetScanNum

Description	Set CTS Scan number
Parameters	R4: Pad Index
Return Values	None
Destroy	R2, R4
Remarks	CTS Driver code will call this function to set pad scan count
Example	F_CTSSetScanNum:

	<pre> r2 = R_ScanNumber r2 = r2 + r4 r2 = [r2] [P_CTS_CYCLE] = r2 retf </pre>
--	---

7.1.4 F_CTSSel

Description	Set CTS Scan IO selection register
Parameters	R4: Pad Index
Return Values	None
Destroy	R2, R4
Remarks	Driver code will call this function to set CTS IO selection register
Example	<pre> F_CTSSel: r2 = seg16 T_CTS_IOSel ds = r2 r2 = T_CTS_IOSel r2 = r2 + r4 r2 = ds:[r2] [P_CTS_CH] = r2 retf </pre>

7.1.5 F_CTSStart

Description	CTS Scanning Start
Parameters	None
Return Values	None
Destroy	R1
Remarks	CTS will call this function to clear CTS TM1 counter and Start CTS Scanning
Example	<pre> F_CTSStart: r1 = [P_CTS_Ctrl1] r1 = r1 (C_CTS_En + C_CTS_Start) [P_CTS_Ctrl1] = r1 retf </pre>

7.1.6 F_CTSAllChOff

Description	Stop All CTS Scan and Clear Scan IO setting
Parameters	None
Return Values	None
Destroy	R1

Remarks	CTS Driver call will call this function to stop CTS Scan and Release CTS IO selection
Example	<pre>F_CTSAllChOff: r1 = [P_CTS_Ctrl1] r1 = r1 & ~(C_CTS_En) [P_CTS_Ctrl1] = r1 retf</pre>

8 Function List for C

CTS Driver Function List			
Function	Parameter	Return	Description
<code>unsigned int F_CTS_Version(void);</code>	None	CTS Driver Code Version	CTS Driver code version
<code>void F_CTS_Initial(void);</code>	None	None	CTS Driver variable and HW Initialize
<code>void F_CTS_ScanStart(void);</code>	None	None	CTS Scanning start
<code>void F_CTS_ISR(void);</code>	None	None	CTS Driver interrupt service
<code>void F_CtsForceCali(unsigned int CalNum);</code>	<code>unsigned int</code> CalNum Calibration Count	None	Force CTS Driver Calibration
<code>void F_CTS_ServiceLoop(void);</code>	None	None	CTS Service loop

9 Application Interface for C

9.1 CTS Driver Code

9.1.1 F_CTS_Version

Description	CTS Driver code version
Header File	CTSDrv.h
Syntax	<code>unsigned int F_CTS_Version(void);</code>
Parameters	None
Return Values	None
Remarks	Programmers can call this function to get CTS Driver library version
Example	<pre>#include CTSDrv.h int Version; int main(void) { Version = F_CTS_Version(); }</pre>

9.1.2 F_CTS_Initial

Description	CTS Driver Variable and HW initialize
Header File	CTSDrv.h
Syntax	<code>void F_CTS_Initial(void);</code>
Parameters	None
Return Values	None
Remarks	Programmers must call this function to initial CTS driver before user CTS function
Example	<pre>#include CTSDrv.h int main(void) { F_CTS_Initial(); }</pre>

9.1.3 F_CTS_ScanStart

Description	CTS Scanning start
Header File	CTSDrv.h
Syntax	<code>void F_CTS_ScanStart(void);</code>
Parameters	None
Return Values	None
Remarks	When this function is called CTS scan will start.
Example	<pre>#include CTSDrv.h int main(void) { F_CTS_Initial(); F_CTS_ScanStart(); }</pre>

9.1.4 F_CTS_ISR

Description	CTS Driver interrupt service
Header File	CTSDrv.h
Syntax	<code>void F_CTS_ISR(void);</code>
Parameters	None
Return Values	None
Remarks	Programmers must service this function in CTS TM0 ISR
Example	<pre>#include CTSDrv.h void IRQ6(void) { *P_CTS_Status = *P_CTS_Status; F_CTS_ISR(); }</pre>

9.1.5 F_CtsForceCali

Description	Force CTS Driver Calibration
Header File	CTSDrv.h
Syntax	<code>void F_CtsForceCali (unsigned int CalNum);</code>
Parameters	<code>unsigned int</code> CaliCnt Calibration Count
Return Values	None
Remarks	Programmers can call this function to for CTS driver calibration
Example	<pre>#include CTSDrv.h int main(void) { F_CtsForceCali(20); }</pre>

9.1.6 F_CTS_ServiceLoop

Description	CTS Service loop
Header File	CTSDrv.h
Syntax	<code>void F_CTS_ServiceLoop(void);</code>
Parameters	None
Return Values	None
Remarks	Programmers must service this function in main loop to process CTS
Example	<pre>#include CTSDrv.h int main(void) { ... While(1){ F_CTS_ServiceLoop(void); ... } }</pre>



	}
--	---

10 Program Example

In maic.c

```
#include "..\include\GPL951_Body.h"
#include "CTSDrv.h"
void main(void)
{
    F_SYS_Initial();
    F_CTS_Initial();
    F_CTS_ScanStart();
    while(1)
    {
        *P_WatchDog_Clear = C_WDT_Clear;
        F_CTS_ServiceLoop();
        if(R_ScanDoneFlag != 0)
        {
            if(R_CTS_Key != R_CtsPreKey)
            {
                i = R_CTS_Key;
                R_CtsPreKey = R_CTS_Key;
                *P_IOC_Data = R_CtsPreKey;
            }
        }
    }
}
```

In isr.c

```
#include CTSDrv.h
void IRQ6 (void)
{
    *P_CTS_Status = *P_CTS_Status;
    F_CTS_ISR();
}
```

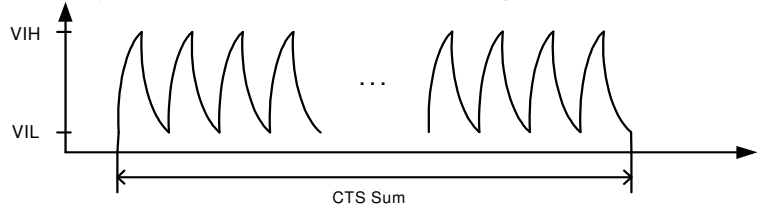
11 Driver Code Variable Definition

Below is CTS variables and constant definition:

Scan Number: This constant definition is used to control the CTS scan number for one cycle.

Scan Cycle: This constant definition is used to control the CTS scan cycle number.

CTS Sum (R_CtsSum): Scan time x Scan Number x Scan Cycle



CTS Reference (R_CtsRefer, R_CtsReferL): No touch CTS Sum average value.

Trigger Level (R_TriggerLevel): Touched and no touch charge CTS Sum delta

On Threshold Level: If CTS trigger level is great than this value, the correspond touch pad bit status will be set to 1.

Off Threshold Level: If CTS trigger level is lower than this value, the correspond touch pad bit status will be set to 0.

Key Status (R_CTS_Key): It will show present Touch status. When touch pad is touched the correspond bit will be set to 1.

12 Special Note

1. In CTSDefine.inc, it has five user's define areas. Programmers need to define the parameters in these five areas before use CTS driver.

//=====User Define Area I =====

```
D_SinglePadNum:      .EQU  8      //CTS Pad Number
D_TraceUpStep:       .EQU  2      //Refence value trace up Max step definatin
D_TraceDownStep:     .EQU  5      //Refence value trace down Max step definatin
D_CalibrationCount:  .EQU  0x30    //Reference value calibration count
D_ReferenceErrCnt:    .EQU  0x20    //Maximmmum value is 127. Reference value error debounce
                                //time defination.
D_CtsKeydebounceTime: .EQU  2      //CTS key debounce count
D_ScanCycleCnt       .EQU  60     //Scan cycle
```

//=====User Define Area II =====

// PadIndex, IOIndex

```
.define CTS_Pad0 0
.define CTS_Pad1 1
.define CTS_Pad2 2
.define CTS_Pad3 3
.define CTS_Pad4 4
.define CTS_Pad5 5
.define CTS_Pad6 6
.define CTS_Pad7 7
.define CTS_Pad8 8
.define CTS_Pad9 9
.define CTS_Pad10 10
.define CTS_Pad11 11
.define CTS_Pad12 12
.define CTS_Pad13 13
.define CTS_Pad14 14
.define CTS_Pad15 15
```

//===== User Define area III =====

// PadIndex, ScanTime

```
.define ScanNum 60

.define Pad0_ScanNum ScanNum
.define Pad1_ScanNum ScanNum
.define Pad2_ScanNum ScanNum
.define Pad3_ScanNum ScanNum
.define Pad4_ScanNum ScanNum
.define Pad5_ScanNum ScanNum
.define Pad6_ScanNum ScanNum
.define Pad7_ScanNum ScanNum
```



```
.define Pad8_ScanNum ScanNum
.define Pad9_ScanNum ScanNum
.define Pad10_ScanNum ScanNum
.define Pad11_ScanNum ScanNum
.define Pad12_ScanNum ScanNum
.define Pad13_ScanNum ScanNum
.define Pad14_ScanNum ScanNum
.define Pad15_ScanNum ScanNum
```

//===== User Define area IV =====

```
// PadIndex, OnLevel
.define TriggLeLv 540
.define OnLv TriggLeLv*7/10
.define Pad0_OnLv OnLv
.define Pad1_OnLv OnLv
.define Pad2_OnLv OnLv
.define Pad3_OnLv OnLv
.define Pad4_OnLv OnLv
.define Pad5_OnLv OnLv
.define Pad6_OnLv OnLv
.define Pad7_OnLv OnLv
.define Pad8_OnLv OnLv
.define Pad9_OnLv OnLv
.define Pad10_OnLv OnLv
.define Pad11_OnLv OnLv
.define Pad12_OnLv OnLv
.define Pad13_OnLv OnLv
.define Pad14_OnLv OnLv
.define Pad15_OnLv OnLv
```

//===== User Define area V =====

```
// PadIndex, OffLevel
.define OffLv TriggLeLv*3/10
.define Pad0_OffLv OffLv
.define Pad1_OffLv OffLv
.define Pad2_OffLv OffLv
.define Pad3_OffLv OffLv
.define Pad4_OffLv OffLv
.define Pad5_OffLv OffLv
.define Pad6_OffLv OffLv
.define Pad7_OffLv OffLv
.define Pad8_OffLv OffLv
.define Pad9_OffLv OffLv
.define Pad10_OffLv OffLv
```

```
.define    Pad11_OffLv    OffLv
.define    Pad12_OffLv    OffLv
.define    Pad13_OffLv    OffLv
.define    Pad14_OffLv    OffLv
.define    Pad15_OffLv    OffLv
```